

CM1408-04DE

4-C
EMI Filter with
Pi-Style EMI Filter
Network
Capacitor-Resistor-Capacitor (C-R-C)
Network
ESD Protection
ESD Protection

Features

- Four Channels of EMI Filtering with Integrated ESD Protection
- Pi-Style EMI Filters in a Capacitor-Resistor-Capacitor (C-R-C) Network
- ±15 kV ESD Protection on Each Channel (IEC 61000-4-2 Level 4, Contact Discharge)
- ±30 kV ESD Protection on Each Channel (HBM)
- Greater than -35 dB Attenuation (Typical) at 1 GHz

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Table 4. ELECTRICAL OPERATING CHARACTERISTICS (Note 1)

Symbol	Parameter	Conditions	Min	Typ	Max	Units
R	Resistance		80	100	120	Ω
C _{TOTAL}	Total Channel Capacitance	At 2.5 VDC Reverse Bias, 1 MHz, 30 mVAC	14	17	22	pF
C	Capacitance C	At 2.5 VDC Reverse Bias, 1 MHz, 30 mVAC		8.5		pF
V _{DIODE}	Standoff Voltage	I _{DIODE} = 10 μ A		6.0		V
I _{LEAK}	Diode Leakage Current (reverse bias)	V _{DIODE} = 3.3 V		0.1	1.0	μ A
V _{SIG}	Signal Clamp Voltage Positive Clamp Negative Clamp	I _{LOAD} = 10 mA I _{LOAD} = -10 mA	5.6 -1.5	6.8 -0.8	9.0 -0.4	V
V _{ESD}	In-system ESD Withstand Voltage a) Human Body Model, MIL-STD-883, Method 3015 b) Contact Discharge per IEC 61000-4-2 Level 4	(Notes 2 and 3)	30 15			kV
R _{DYN}	Dynamic Resistance Positive Negative			2.3 0.9		Ω
f _C	Cut-off Frequency Z _{SOURCE} = 50 Ω , Z _{LOAD} = 50 Ω	Channel R = 100 Ω , Channel C _{SINGLE} = 8.5 pF		200		MHz

1. T_A = 25°C unless otherwise specified.
2. ESD applied to input and output pins with respect to GND, one at a time.
3. These parameters are guaranteed by design and characterization.

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PERFORMANCE INFORMATION

Typical Filter Performance ($T_A = 25^\circ\text{C}$, DC Bias = 0 V, 50 Ω Environment)

1: -5.328 dB

Figure 1. Insertion Loss vs. Frequency (FILTER1 Input to GND)



Figure 2. Insertion Loss vs. Frequency (FILTER2 Input to GND)

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PERFORMANCE INFORMATION (Cont'd)

Typical Filter Performance ($T_A = 25^\circ\text{C}$, DC Bias = 0 V, 50 Ω Environment)

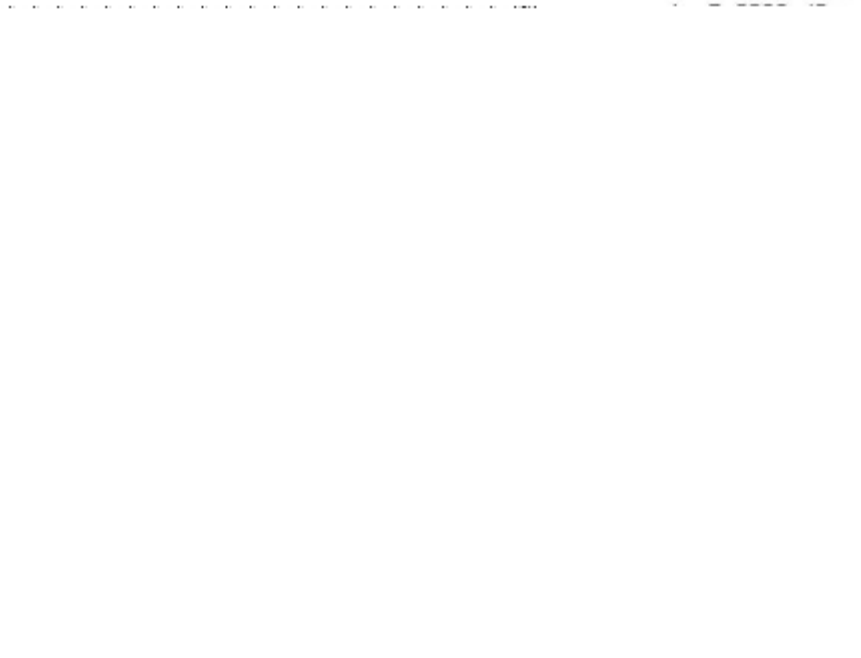


Figure 3. Insertion Loss vs. Frequency (FILTER3 Input to GND)

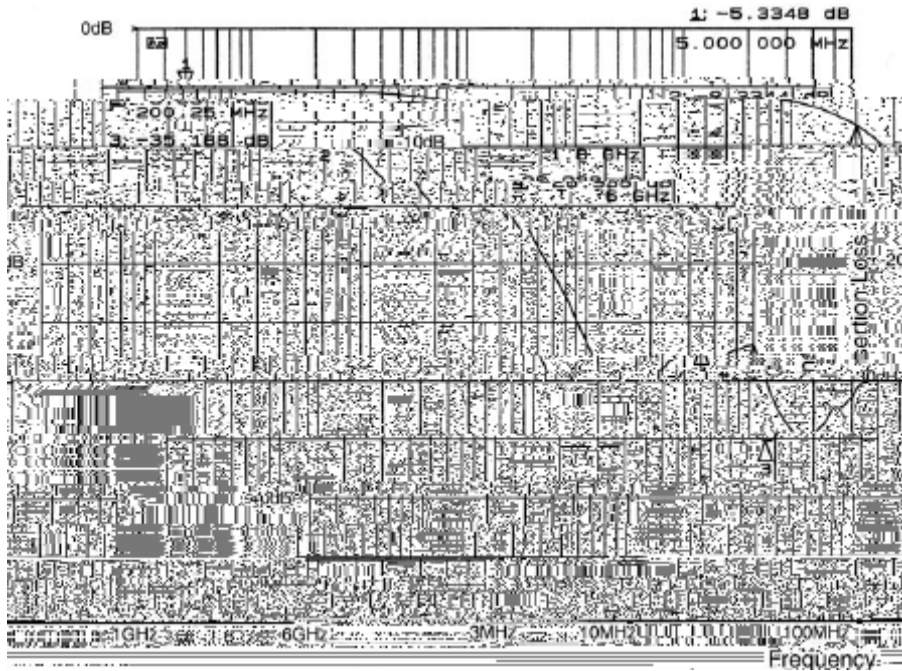
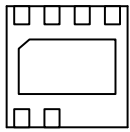


Figure 4. Insertion Loss vs. Frequency (FILTER4 Input to GND)

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