

System Basis Chip with CAN FD, LDO Regulator and Wake-up Comparator

NCV7451

The system basis chip (SBC) NCV7451 integrates +5 V / 250 mA LDO regulator with a high speed CAN FD transceiver and local wake up comparator, directly controlled by dedicated pins.

Features

- 5 V \pm 2% / 250 mA LDO
 - ◆ Current Limitation with Fold back
 - ◆ Output Voltage Monitoring
- One High Speed CAN FD Transceiver
 - ◆ Compliant to ISO11898 2:2016
 - ◆ CAN FD Timing Specified up to 5 Mbps
 - ◆ Current Limitation, Reverse Current Protected
 - ◆ TxDC Timeout
- Local Wake up Comparator
 - ◆ Integrated Pull up / Pull down Current Source
- Very Low Current Quiescent Consumption
- Window Watchdog
- Direct Control
- Thermal Shutdown Protection
- AEC Q100 Qualified and PPAP Capable
- Wetable Flank Package for Enhanced Optical Inspection
- This is a Pb Free Device

Typical Applications

- Automotive
- Industrial Networks



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DFNW14 4.5x3, 0.65P
CASE 507AC

MARKING DIAGRAM

NCV7451 = Specific Device Code
A = Assembly Location
L = Wafer Lot
Y = Year
W = Work Week
▪ = Pb-Free Package

PIN CONNECTIONS

[1]
[2]
[]

ORDERING INFORMATION

| Device | Package | Shipping [†] |
|---------------|---------------------|-----------------------|
| NCV7451MW0R2G | DFNW14 (Pb-Free) | 5000 / Tape & Reel |

[†]For information on tape and reel specifications, including part orientation and tape sizes, please refer to our Tape and Reel Packaging Specifications Brochure, BRD8011/D.

NCV7451

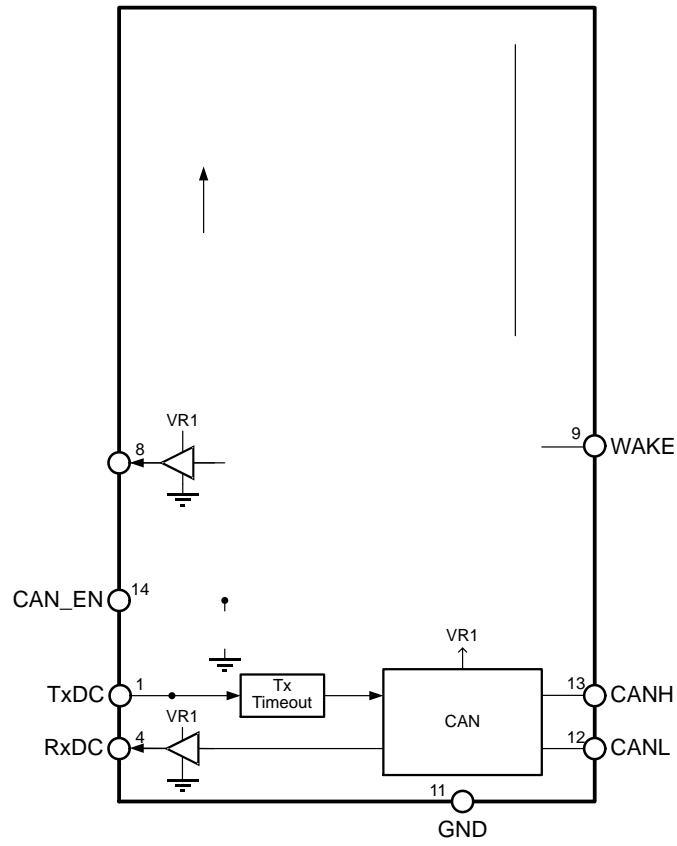


Figure 2. Block Diagram

NCV7451

MAXIMUM RATINGS

| Symbol | Rating | Min | Max | Unit | |
|--------------------|--|---------------------------|-------------------------------------|------|----|
| VS | DC Power Supply Voltage (Note 1) | -0.3 | +40 | V | |
| VR1 | LDO Supply pin output voltage | -0.3 | 6 or VS+0.3 (whichever is lower) | V | |
| digIO | DC voltage on digital pins (CAN_EN, WD_EN, WDI, RSTN, RxDC, TxDC, WAKE_OUT) | -0.3 | VR1+0.3 | V | |
| WAKE | DC WAKE pin Input Voltage | -40 | +40 | V | |
| CANH, CANL | DC voltage on pin CANH and CANL | -40 | +40 | V | |
| Vdiff | Differential DC voltage between any two pins (incl. CANH and CANL) | -40 | +40 | V | |
| ESD _{HBM} | ESD capability, Device HBM, according to AEC-Q100-002 (EIA/JESD22-A114); (Note 2) | Pins VS, CANH, CANL, WAKE | -8 | +8 | kV |
| | | Other pins | -4 | +4 | |
| ESD _{MM} | ESD capability; MM, according to AEC-Q100-003 (EIA/JESD22-A115); all pins | -200 | +200 | V | |
| ESD _{CDM} | ESD capability; CDM, according to AEC-Q100-011 (EIA/JESD22-C101); all pins | -750 | +750 | V | |
| ESD _{IEC} | ESD capability; System HBM, according to IEC61000-4-2; pins VS, CANH, CANL, WAKE; (Note 3) | -6 | +6 | kV | |
| SCHAF | Voltage transients, Test pulses According to ISO7637-2, Class D; pins VS, CANH, CANL, WAKE | Test pulse 1 | -100 | - | V |
| | | Test pulse 2a | - | +75 | V |
| | | Test pulse 3a | -150 | - | V |
| | | Test pulse 3b | - | +100 | V |
| Tj | Junction Temperature Range | -40 | +150 | °C | |
| Tstg | Storage Temperature Range | -55 | +150 | °C | |

NCV7451

RECOMMENDED OPERATING RANGES

| Rating | Min | Max | Unit |
|--|-----|-----|------|
| Functional supply voltage | 5.0 | 28 | V |
| Supply voltage for valid parameter specification | 6.0 | 18 | V |
| VR1 regulator output voltage | 4.9 | 5.1 | V |
| VR1 regulator output current (including CAN transceiver consumption) | 0 | 250 | mA |
| Digital inputs/outputs voltage | 0 | VR1 | V |
| WAKE input voltage | 0 | VS | V |
| CAN bus pins voltage | -40 | 40 | V |
| Junction Temperature | -40 | 150 | °C |
| Ambient Temperature | -40 | 125 | °C |

Operation above the stresses listed in the Recommended Operating Ranges is not implied. Extended exposure to stresses beyond Recommended Operating Ranges limits may affect device reliability.

CHARACTERISTICS

$-40^{\circ}\text{C} \leq T_j \leq 150^{\circ}\text{C}$; $4.75\text{ V} \leq \text{VR1} \leq 5.25\text{ V}$; $R_{LT} = 60\ \Omega$, $C_{LT} = 100\ \mu\text{F}$, C_{ST} not used, unless otherwise specified.

| Parameter | Conditions | Min | Typ | Max | Unit |
|---------------------------|---|-----|-----|-----|------|
| | VS rising | 3.4 | - | 4.1 | V |
| VS POR threshold | VS falling | 2.0 | - | 3.5 | V |
| VS consumption, low-power | VS = 14 V, VR1 on (not loaded), WAKE floating, CAN bus recessive, CAN_EN = Low, WD_EN = Low, $T_j \leq 85^{\circ}\text{C}$ | - | 28 | 35 | A |
| VS consumption, active | VS = 14 V, VR1 on (loaded by 100 mA, not included in I_{s_act}), WAKE floating, CAN bus recessive, CAN_EN = High, WD_EN = High, TxDC = High | - | 3.7 | 5.0 | mA |

REGULATOR

| | | | | | |
|------------------------------|--|-----|---------------------------|-----|----|
| Regulator output voltage | $0\text{ mA} \leq I(\text{VR1}) \leq 250\text{ mA}$ (including internal CAN consumption), $6\text{ V} \leq \text{VS} \leq 28\text{ V}$ | 4.9 | 5.0 | 5.1 | V |
| Regulator current limitation | Maximum VR1 overload current, $\text{VR1} > \text{RES_VR1}$ | 250 | - | 650 | mA |
| Regulator short current | Maximum VR1 short current, $\text{VR1} < \text{RES_VR1}$ | 125 | $1/2 \times I_{lim_VR1}$ | 325 | mA |
| Dropout Voltage | $I(\text{VR1}) = 100\text{ mA}$, $\text{VS} = 5\text{ V}$ | - | 0.2 | 0.4 | V |
| | $I(\text{VR1}) = 100\text{ mA}$, $\text{VS} = 4.5\text{ V}$ | - | 0.2 | 0.5 | |
| | $I(\text{VR1}) = 50\text{ mA}$, $\text{VS} = 4.5\text{ V}$ | - | 0.1 | 0.4 | |
| Load Regulation | $1\text{ mA} \leq I(\text{VR1}) \leq 100\text{ mA}$ | -50 | - | 50 | mV |
| Line Regulation | $I(\text{VR1}) \leq 100\text{ mA}$ | -40 | - | - | mV |

NCV7451

ELECTRICAL CHARACTERISTICS (continued)

6 V ≤ VS ≤ 18 V; -40°C ≤ Tj ≤ 150°C; 4.75 V ≤ VR1 ≤ 5.25 V; R_{LT} = 60 Ω, C_{LT} = 100 pF, C_{ST} not used, unless otherwise specified.

| Symbol | Parameter | Conditions | Min | Typ | Max | Unit |
|--------|-----------|------------|-----|-----|-----|------|
|--------|-----------|------------|-----|-----|-----|------|

VR1 VOLTAGE REGULATOR

| |
|------------|
| Is_add_VR1 |
|------------|

NCV7451

ELECTRICAL CHARACTERISTICS (continued)

6 V ≤ VS ≤ 18 V; -40°C ≤ Tj ≤ 150°C; 4.75 V ≤ VR1 ≤ 5.25 V; R_{LT} = 60 Ω, C_{LT} = 100 pF, C_{ST} not used, unless otherwise specified.

| Symbol | Parameter | Conditions | Min | Typ | Max | Unit |
|--------|-----------|------------|-----|-----|-----|------|
|--------|-----------|------------|-----|-----|-----|------|

CAN f522.312 698.8k(.68036 ref134.476346 0 TDNES001Pins 763H and 763L)Tj(5.25 V)35..0-TD:0sLT

NCV7451

ELECTRICAL CHARACTERISTICS (continued)

6 V ≤ VS ≤ 18 V; -40°C ≤ Tj ≤ 150°C; 4.75 V ≤ VR1 ≤ 5.25 V; R_{LT} = 60 Ω, C_{LT} = 100 pF, C_{ST} not used, unless otherwise specified.

| Symbol | Parameter | Conditions | Min | Typ | Max | Unit |
|--------|-----------|------------|-----|-----|-----|------|
|--------|-----------|------------|-----|-----|-----|------|



undervoltage / overvoltage, the CAN transceiver is in its wake up detection state. Logical level on TxDC is ignored and pin RxDC is kept high until a CAN bus wake up is detected. The CAN bus wake up corresponds to a pattern consisting of dominant – recessive – dominant symbols of at least t_{wake_filt} each. The RxDC starts following the CAN bus afterwards. The pattern must be received within t_{wake_to} to be recognized as a valid wake up event, otherwise internal wake up logic is reset.

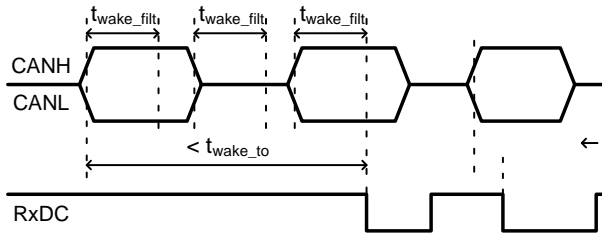


Figure 9. CAN Wake up Pattern

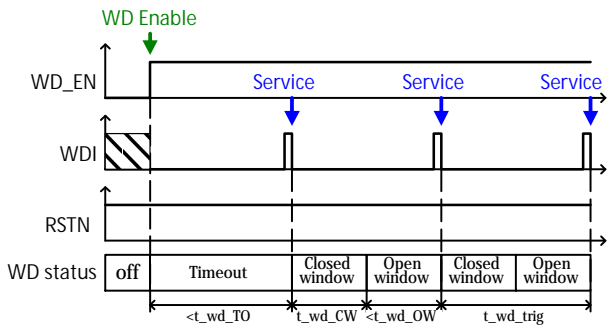


Figure 12. Correct Watchdog Services

In case the watchdog is not triggered before the timeout or open window elapses (Figure 13, Figure 14), or trigger is sent within the closed window (Figure 15), RSTN signal is generated and then watchdog restarted in the timeout mode again.

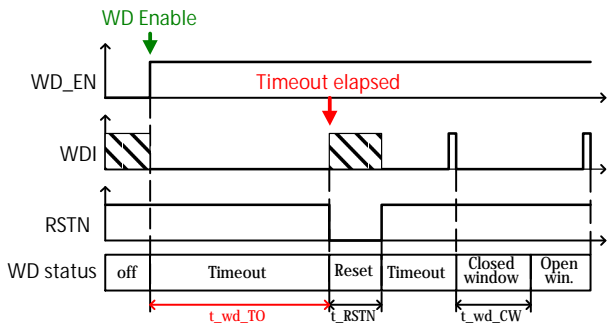


Figure 13. Missed Watchdog in Timeout Mode

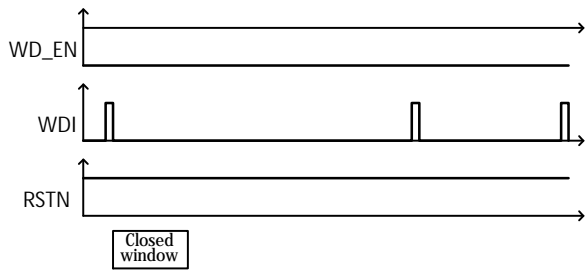


Figure 14. Missed Watchdog in Window Mode

NCV7451

Operating Modes

The device operating modes are directly controlled by CAN_EN input pin and failure events (see Figure 17).

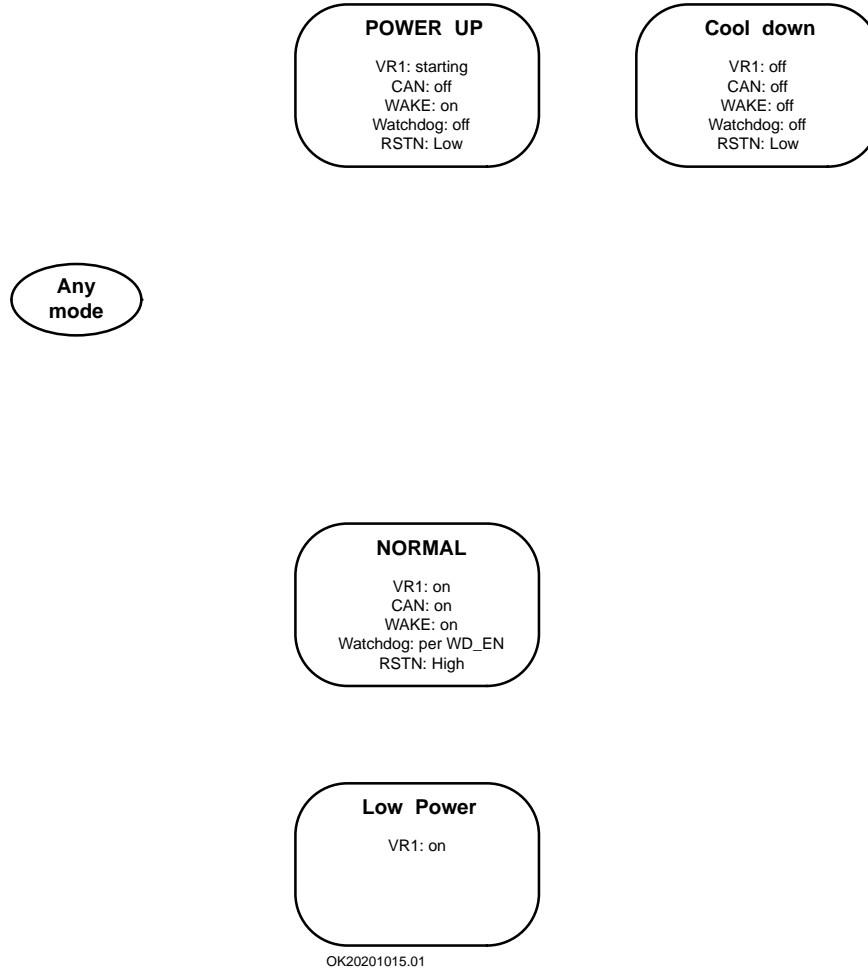


Figure 17. Operating Modes Diagram

ISO11898 2:2016 PARAMETER CROSS REFERENCE TABLE

NCV7451

ISO11898 2:2016 PARAMETER CROSS REFERENCE TABLE (continued)

| ISO 11898 2:2016 Specification | | NCV7451 Datasheet |
|---|--|----------------------------|
| Parameter | Notation | Symbol |
| DATA SIGNAL TIMING REQUIREMENTS for use with bit rates above 2 Mbit/s and up to 5 Mbit/s | | |
| Transmitted recessive bit width @ 5 Mbit/s | $t_{\text{Bit(Bus)}}$ | $t_{\text{Bit(Vi(diff))}}$ |
| Transmitted recessive bit width @ 5 Mbit/s | $t_{\text{Bit(RXD)}}$ | $t_{\text{Bit(RxDC)}}$ |
| Received recessive bit width @ 5 Mbit/s | t_{Rec} | t_{Rec} |
| MAXIMUM RATINGS OF $V_{\text{CAN_H}}$, $V_{\text{CAN_L}}$ AND V_{DIFF} | | |
| Maximum rating V_{Diff} | V_{Diff} | Vdiff |
| General maximum rating $V_{\text{CAN_H}}$ and $V_{\text{CAN_L}}$ | $V_{\text{CAN_H}}$ $V_{\text{CAN_L}}$ | CANH CANL |
| Optional: Extended maximum rating $V_{\text{CAN_H}}$ and $V_{\text{CAN_L}}$ | $V_{\text{CAN_H}}$ $V_{\text{CAN_L}}$ | NA |
| MAXIMUM LEAKAGE CURRENTS ON CAN_H AND CAN_L, UNPOWERED | | |
| Leakage current on CAN_H, CAN_L | $I_{\text{CAN_H}}$, $I_{\text{CAN_L}}$ | I_{LI} |
| BUS BIASING CONTROL TIMINGS | | |
| CAN activity filter time, long | t_{Filter} | NA |
| CAN activity filter time, short | t_{Filter} | $t_{\text{wake_filt}}$ |
| Optional: Wake-up timeout, short | t_{Wake} | NA |
| Optional: Wake-up timeout, long | t_{Wake} | $t_{\text{wake_to}}$ |
| Timeout for bus inactivity (Required for selective wake-up implementation only) | t_{Silence} | NA |
| Bus Bias reaction time (Required for selective wake-up implementation only) | t_{Bias} | NA |

NCV7451

PACKAGE DIMENSIONS

DFNW14 4.5x3, 0.65P

