# **Deca Half-Bridge Driver**

The NCV7720 Deca is a ten channel half-bridge driver with protection features designed specifically for automotive and industrial motion control applications. The product has independent controls and diagnostics, and the drivers can be operated in forward, reverse, brake, and high impedance states. The device is controlled via a 16 bit SPI interface and is daisy chain compatible.

### Features

- Low Quiescent Current Sleep Mode
- High–Side and Low–Side Drivers Connected in Half–Bridge Configurations
- Integrated Freewheeling Protection (LS and HS)
- 0.55 A Peak Current
- $R_{DS(on)} = 1.0 \Omega (typ)$
- 5 MHz SPI Communication
- 16 Bit Frame Error Detection
- Daisy Chain Compatible with Multiple of 8 bit Devices
- Compliance with 3.3 V and 5 V Systems
- Undervoltage and Overvoltage Lockout
- Discriminated Fault Reporting
- Over Current Protection
- Over-temperature Protection
- Underload Detection
- Exposed Pad Package
- NCV Prefix for Automotive and Other Applications Requiring Unique Site and Control Change Requirements; AEC–Q100 Qualified and PPAP Capable
- This is a Pb–Free Device

### **Typical Applications**

- Automotive
- Industrial

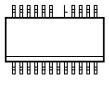


# **WN** Semiconductor

www.onsemi.com



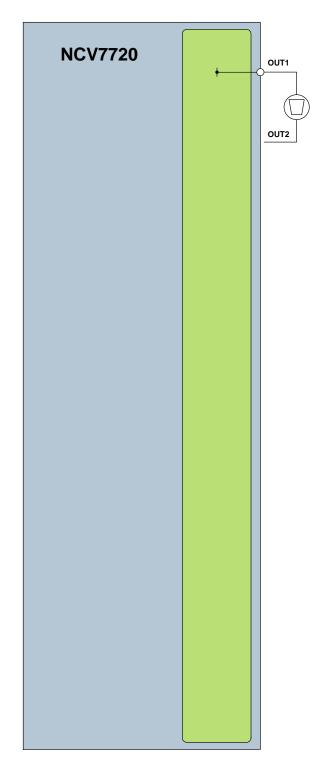
### MARKING DIAGRAM

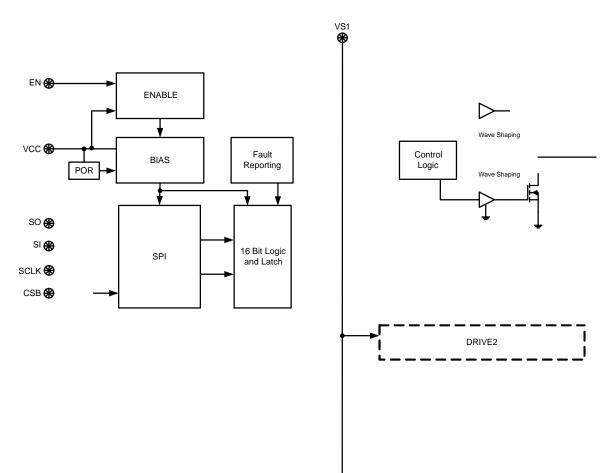


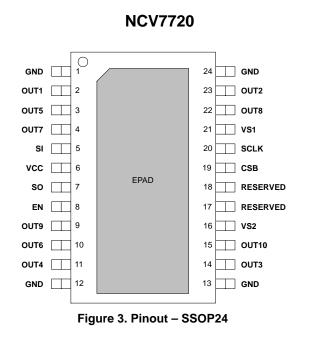
### ORDERING INFORMATION

See detailed ordering and shipping information on page 24 of this data sheet.

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PIN FUNCTION DESCRIPTION The pin-out for the Deca Half-Bridge in SSOP24 package is shown in the table below.

Pin# SSOP24	Symbol	Description
1	GND	Ground
2	OUT1	Half-bridge output 1
3	OUT5	Half-bridge output 5
4	OUT7	Half-bridge output 7
5	SI	16 bit serial communication input. 3.3V/5V (TTL) Compatible – internally pulled down.
6	VCC	Power supply input for Logic.
7	SO	16 bit serial communication output. 3.3V/5V Compliant
8	EN	Enable – active high; wakes the device from sleep mode. 3.3V/5V (TTL) Compatible – internally pulled down.
9	OUT9	Half-bridge output 9
10	OUT6	Half-bridge output 6
11	OUT4	Half-bridge output 4
12	GND	Ground
13	GND	Ground
14	OUT3	Half-bridge output 3
15	OUT10	Half-bridge output 10
16	VS2	Power Supply input for outputs 3, 4, 6, 9, and 10. This pin must be connected to VS1 externally.
17	Reserved	Factory use – connect to GND or leave unconnected – internally pulled down.
18	Reserved	Factory use – connect to GND or leave unconnected – internally pulled down.
19	CSB	Chip select bar – active low; enables serial communication operation. 3.3V/5V (TTL) Compatible – internally pulled up.
20	SCLK	

### MAXIMUM RATINGS (Voltages are with respect to GND)

	Rating	Symbol	Value	Unit
VSx Pin Voltage	(VS1, VS2) (DC) (AC), t < 500 ms, Ivsx > -2 A	VSxdcMax VSxac	-0.3 to 40 -1.0	V

-1.0-1.0

#### ELECTRICAL CHARACTERISTICS

 $(-40^{\circ}C \leq T_J \leq 150^{\circ}C, \, 5.5 \text{ V} \leq \text{VSx} \leq 40 \text{ V}, \, 3.15 \text{ V} \leq \text{V}_{CC} \leq 5.25 \text{ V}, \, \text{EN} = \text{V}_{CC}, \, \text{unless otherwise specified.})$ 

Characteristic	Symbol	Conditions	<b>M</b> /Fr2 1	Tf0 <b>Typ</b> 408	3.75 <b>161.550</b> 7.′	.061 <b>Uīrdi0</b> a5
POWER SUPPLIES		·				
Supply Current (VS1 + VS2) Sleep Mode	lqVSx85	VS1 = VS2 = 13.2V, V <sub>CC</sub> = 0 V -40°C to 85°C	-	1.0	2.5	μΑ
Supply Current (VS1 + VS2) Active Mode	lvsOp	EN = V <sub>CC</sub> , 5.5V < VSx < 28 V No Load	-	2.5	5.0	mA
Supply Current (Vcc) Sleep Mode	IqV <sub>CC</sub>	$CSB = V_{CC}, EN = SI = SCLK = 0 V$ $-40^{\circ}C \text{ to } 85^{\circ}C$ $EN = CSB = V_{CC}, SI = SCLK = 0V$	-	1.0	2.5	μΑ
Active Mode	IV <sub>CC</sub> Op	No Load	-	1.5	3.0	mA
Total Sleep Mode Current I(VS1) + I(VS2) + I(VCC)	lqTot	Sleep Mode, -40°C to 85°C VS1 = VS2 = 13.2 V, No Load	-	2.0	5.0	μΑ
VCC Power-on Reset Threshold	V <sub>CC</sub> por	V <sub>CC</sub> increasing	-	2.55	2.90	V
VSx Undervoltage Detection Threshold	VSxuv	VSx decreasing	3.5	4.1	4.5	V
VSx Undervoltage Detection Hysteresis	VSxuHys		100	-	450	mV
VSx Overvoltage Detection Threshold	VsXov	VSx increasing	30	36	40	V
VSx Overvoltage Detection Hysteresis	VSxoHys		1	2B5T8(	V)5644713	386.58/6 562

#### DRIVER OUTPUT CHARACTERISTICS

Output High R<sub>DS(on)</sub> (source)

 $R_{\text{DSon}}$ HS

ELECTRICAL CHARACTERISTICS

(-40°C  $\leq$  T\_J  $\leq$  150°C, 5.5 V  $\leq$ 

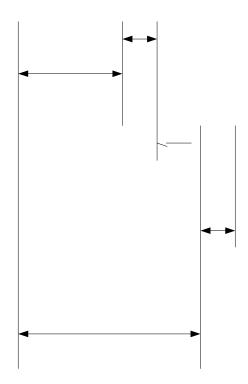
#### ELECTRICAL CHARACTERISTICS

 $(-40^{\circ}C \leq T_J \leq 150^{\circ}C, \, 5.5 \text{ V} \leq \text{VSx} \leq 40 \text{ V}, \, 3.15 \text{ V} \leq \text{V}_{CC} \leq 5.25 \text{ V}, \, \text{EN} = \text{V}_{CC}, \, \text{unless otherwise specified.})$ 

#### SERIAL PERIPHERAL INTERFACE

Characteristic	Symbol	Conditions	Timing Charts #	Min	Тур	Max	Unit
CSB Setup Time	TcsbSup		5, 6	100	-	-	ns
CSB High Time	TcsbH	(Note 5)	7				

### CHARACTERISTIC TIMING DIAGRAMS



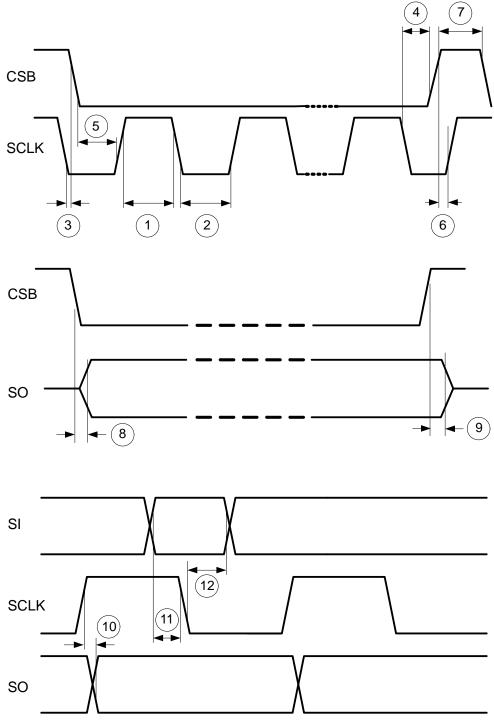
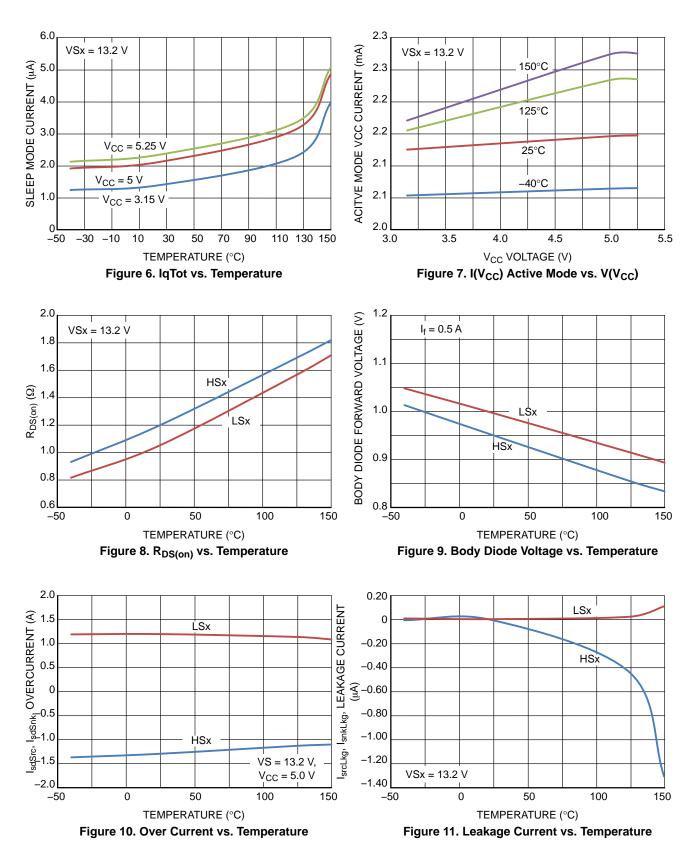


Figure 5. Detailed SPI Timing

### **TYPICAL PERFORMANCE CURVES**



### DETAILED OPERATING DESCRIPTION

### **General Overview**

The NCV7720 is comprised of twenty power drivers (10 PMOS high–side and 10 NMOS low–side). The drivers are

#### Table 1. SPI COMMAND INPUT DEFINITIONS

		Channels 10 –	7 (Input Bit # 14 = 1)	
Bit#	Name	Function	Status*	Scope
15	SRR	Status Register Reset**	1 = Reset	Status Reset per HBSEL
14	HBSEL	Channel Group Select	1 = HB [10:7]	1 = HB [10:7]   0 = HB [6:1]
13	ULDSC	Underload Shutdown	1 = Enabled	Enabled per <b>HBSEL</b> ; Per Half–Bridge Operation
12	х	Natiland		
11		Not Used	-	-
10	HBEN10	Enable Half-Bridge 10		
9	HBEN9	Enable Half–Bridge 9	0 = Hi–Z	Devider Drive
8	HBEN8	Enable Half–Bridge 8	1 = Enabled	Per Half–Bridge
7	HBEN7	Enable Half–Bridge 7		
6	X			
5	X	Not Used	-	-
4	HBCNF10	Configure Half-Bridge 10		
3	HBCNF9	Configure Half–Bridge 9	0 = LS On, HS Off	
2	HBCNF8	Configure Half–Bridge 8	1 = LS Off, HS On	Per Half–Bridge
1	HBCNF7	Configure Half–Bridge 7		
0	OVLO	VSx Overvoltage Lockout	1 = Enabled	Global Lockout
	•	Channels 6 –	1 (Input Bit # 14 = 0)	
Bit#	Name	Function	Status*	Scope
15	SRR	Status Register Reset**	1 = Reset	Status Reset per HBSEL
14	HBSEL	Channel Group Select	0 = HB [6:1]	1 = HB [10:7]   0 = HB [6:1]
13	ULDSC	Underload Shutdown	1 = Enabled	Enabled per <b>HBSEL</b> ; Per Half–Bridge Operation
12	HBEN6	Enable Half–Bridge 6		
11	HBEN5	Enable Half–Bridge 5		
10	HBEN4	Enable Half–Bridge 4	0 = Hi–Z	
9	HBEN3	Enable Half–Bridge 3	1 = Enabled	Per Half–Bridge
8	HBEN2	Enable Half–Bridge 2	1	
7	HBEN1	Enable Half–Bridge 1	1	
6	HBCNF6	Configure Half–Bridge 6		
5	HBCNF5	Configure Half–Bridge 5	1	
4	HBCNF4	Configure Half–Bridge 4	0 = LS On, HS Off	
3	HBCNF3	Configure Half–Bridge 3	1 = LS Off, HS On	Per Half–Bridge
2	HBCNF2	Configure Half–Bridge 2	┥	
1	HBCNF1	Configure Half–Bridge 1	┥ │	
0	OVLO	VSx Overvoltage Lockout	1 = Enabled	Global Lockout

\*All command input bits are set to 0 at V<sub>CC</sub> power–on reset. \*\*Latched faults are cleared and outputs can be re–programmed if no fault exists after SRR asserted.

### **Table 2. SPI STATUS OUTPUT DEFINITIONS**

Channels 10 – 7 (Input Bit # 14 = 1)					
Bit#	Name Function Status*		Status*	Scope	
PRE_15	TSD	Latched Thermal Shutdown	1 = Fault	Global Notification; Per Half–Bridge Operation	
15	ocs	Latched Overcurrent Shutdown	1 = Fault	Notification per <b>HBSEL</b> ; Per Half–Bridge Operation	
14	PSF	VS1 and/or VS2 Undervoltage or Overvoltage	1 = Fault	Global Notification and Global Operation	
13	ULD	Underload Detect	1 = Fault	Notification per <b>HBSEL</b> ; Per Half–Bridge Operation	
12	х	Not Used	(Hard coded to zero)		
11	~	Not Osed	(Hard coded to zero)	_	
10	HBST10	Half-Bridge 10 Output Status			
9	HBST9	Half-Bridge 9 Output Status	0 = Hi–Z		
8	HBST8	Half-Bridge 8 Output Status	1 = Enabled	Per Half–Bridge	
7	HBST7	Half-Bridge 7 Output Status			
6	Y.				
5	Х	Not Used	(Hard coded to zero)	-	
4	HBCR10	Half-Bridge 10 Config Status			
3	HBCR9	Half-Bridge 9 Config Status	0 = LS On, HS Off		
2	HBCR8	Half-Bridge 8 Config Status	1 = LS Off, HS On**	Per Half–Bridge	
1	HBCR7	Half–Bridge 7 Config Status	1		
0	TW	Thermal Warning	1 = Fault	Global Notification; Per Half–Bridge Operation	

\*All status output bits are set to 0 at Vcc power–on reset (POR). \*\*HBCRx is forced to 0 when HBSTx = 0 via POR, SPI, or fault.

#### Table 2. SPI STATUS OUTPUT DEFINITIONS

Channels 6 – 1 (If Previous Input Bit # 14 = 0)						
Bit#	Name	Function	Status*	Scope		
PRE_15	TSD	Latched Thermal Shutdown	1 = Fault	Global Notification; Per Half–Bridge Operation		
15	OCS	Latched Overcurrent Shutdown	1 = Fault	Notification per <b>HBSEL</b> ; Per Half–Bridge Operation		
14	PSF	VS1 and/or VS2 Undervoltage or Overvoltage	1 = Fault			

 $\begin{array}{l} \mbox{CMD } [x,\,n] = \mbox{Command Word to Device `x', Length `n'} \\ \mbox{STA } [x,\,n] = \mbox{Status Word from Device `x', Length `n'} \\ \end{array}$ 

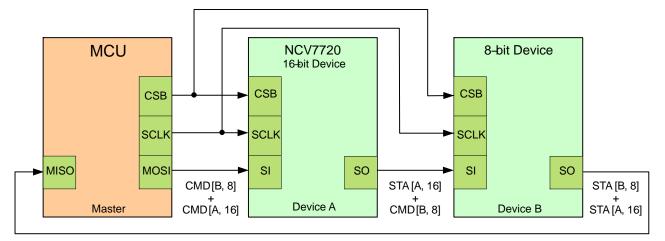
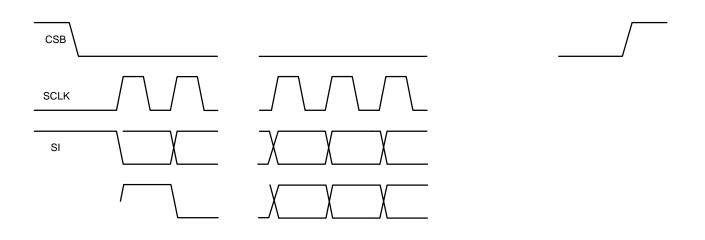
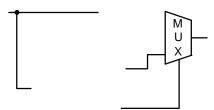


Figure 13. Daisy Chain Configuration





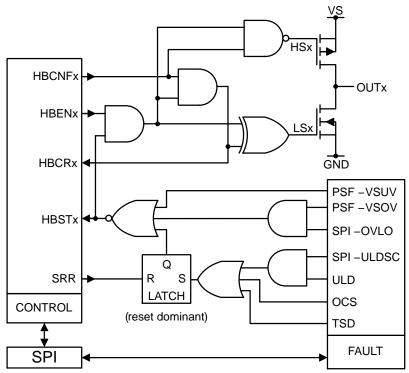


Figure 18. Simplified Half–Bridge Control Logic

Comr	nand	Sta		
HBENx	HBCNFx	HBSTx	HBCRx	OUTx
Х	Х	0	0	Z
0	Х	0	0	Z
1	0	1	0	GND
1	1	1	1	VS

### DIAGNOSTICS, PROTECTIONS, STATUS REPORTING AND RESET

#### Overview

The NCV7720 employs diagnostics designed to prevent destructive overstress during a fault condition. Diagnostics are classified as either supervisory or protection functions (Table 4). Supervisory functions provide status information about device conditions. Protection functions provide status information and activate fault management behaviors.

Diagnostics resulting in output shutdown and latched status may depend on a qualifier and may require user

intervention for output recovery and status memory clear. Diagnostics resulting in output lockout and non–latched status (VSOV or VSUV) may recover and clear automatically. Output configurations can be changed during output lockout. Outputs assume the new configurations or resume the previous configurations when an auto–recover fault is resolved. Table 5 shows output states during faults and output recovery modes, and Table 6 shows the status memory and memory clear modes.

Name	Class	Function
TSD	Protection	Thermal Shutdown
OCS	Protection	Overcurrent Shutdown
PSF	Supervisory	Under/overvoltage Lockout
ULD	Protection	Underload Shutdown
HBSTX	Supervisory	Half-Bridge X Output Status
HBCRX	HBCRX Supervisory Half–Bridge X Config Status	
TW	Supervisory	Thermal Warning

**Table 4. Diagnostic Classes and Functions** 

#### **Status Information Retrieval**

Current status information as selected by HBSEL is retrieved during each SPI frame. To preserve device configuration and output states, the previous SI data pattern must be sent during the status retrieval frame.

Status information is prevented from being updated during a SPI frame but new status becomes available after CSB goes high at the end of the frame provided the frame did not contain an SRR request. For certain device faults, it may not be possible to determine which channel (or channels) has a particular fault (or faults) since notification may be via a single global status bit. The complete status data from all channels may need to be examined to determine where a fault may exist.

#### Status Register Reset – SRR

Sending SRR = 1 clears status memory and re-activates faulted outputs for channels as selected by HBSEL. The previous SI data pattern must be sent with SRR to preserve device configuration and output states. SRR takes effect at the rising edge of CSB and a timer (Tsrr) is started. Tsrr is the minimum time the user must wait between consecutive SRR requests. If a fault is still present when SRR is sent, protection can be re-engaged and shutdown can recur. The device can also be reset by toggling the EN pin or by VCC power-on reset.

#### **Diagnostics Details**

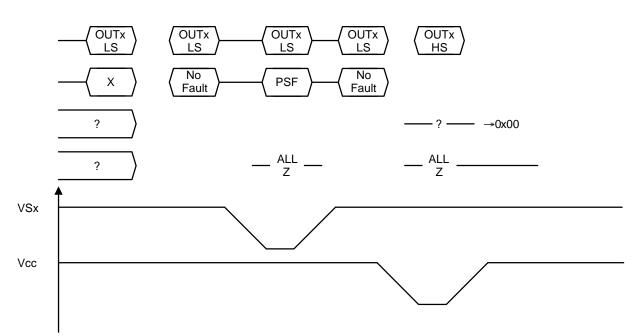
The following sections describe the individual diagnostics and some behaviors. In each description and illustration, a SPI frame is assumed to always be valid and the SI data pattern sent for HBCNFx and HBENx is the same as the previous frame. Actual results can depend on asynchronous fault events and SPI clock frequency and frame rate.

#### Undervoltage Lockout

#### Global Notification, Global Operation

Undervoltage detection and lockout control is provided by monitoring the VS1, VS2 and  $V_{CC}$  supply inputs. Undervoltage hysteresis is provided to ensure clean detection transitions. Undervoltage timing is shown in Figure 19.

Undervoltage at either VSx input turns off all outputs and sets the power supply fail (PSF) status bit. The outputs return to their previously programmed state and the PSF status bit is cleared when VSx rises above the hysteresis voltage level. SPI is available and programmed output enable and configuration states are maintained if proper  $V_{CC}$  is present during VSx undervoltage.  $V_{CC}$  undervoltage turns all outputs off and clears the command input and status output registers.



#### **Underload Shutdown**

### Notification per HBSEL, Shutdown per HBSEL

Underload detection and shutdown control is provided by monitoring each LS driver. Underload timing is shown in Figure 22. Underload at a LS driver starts the global underload delay timer. If underload occurs in another channel after the global timer has been started, the delay for any subsequent underload will be the remainder of the timer. The timer runs continuously with a persistent underload condition.

If underload exists after the delay and if the underload shutdown (ULDSC) command bit is set, both HS and LS drivers are latched off and the underload (ULD) status bit is set; otherwise the drivers remain on and the ULD bit is set (see Table 5 and 6). The ULD bit is cleared and channels are re-activated by sending SRR = 1. The channel group select (HBSEL) input bit determines which channels are affected by SRR and also determines which half-bridges are latched off via the ULDSC command bit (see Table 1).

Underload may result from a fault (e.g. open-load) condition or normal circuit behavior (e.g. L/R tau). In motor applications it is often desirable to actively brake the motor by turning on both HS or LS drivers in two half-bridge channels. If the configuration is two LS drivers (LS brake), an underload will result as the motor current decays normally. Utilizing HS brake instead will avoid underload notification.



#### Thermal Warning and Thermal Shutdown

#### Global Notification, Per Half-Bridge Operation

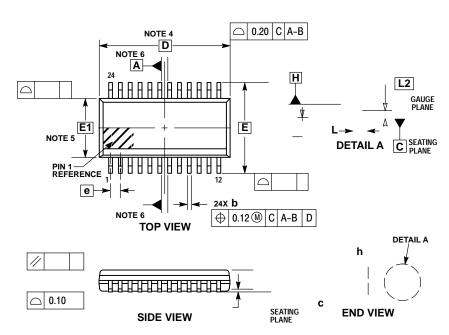
Thermal warning (TW) and thermal shutdown (TSD) detection and control are provided for each half-bridge by monitoring the driver pair's thermal sensor. Thermal hysteresis is provided for each of the warning and shutdown functions to ensure clean detection transitions. Since TW notification precedes TSD, software polling of the TW bit enables avoidance of thermal shutdown. Thermal warning and shutdown timing is shown in Figure 23.

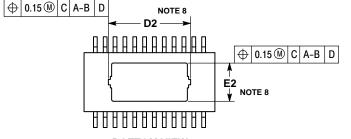
The TW status bit is set when a half-bridge's sensor temperature exceeds the warning level  $(T_J > Twr)$ , and the

bit is automatically cleared when sensor temperature falls below the warning hysteresis level ( $T_J < TwHy$ ). A channel's output state is unaffected by TW.

When sensor temperature exceeds the shutdown level ( $T_J > Tsd$ ), the channel's HS and LS drivers are latched off, the TW bit is/remains set, and the TSD (PRE\_15) bit is set. The TSD bit is cleared and all affected channels in a group are re–activated ( $T_J < TsdHy$ ) by sending SRR = 1. The channel group select (HBSEL) input bit determines which channels are affected by SRR.

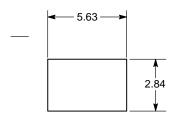






**BOTTOM VIEW** 

SOLDERING FOOTPRINT



- NOTES:
- DIMENSIONING AND TOLERANCING PER ASME Y14.5M, 1994.
   CONTROLLING DIMENSION: MILLIMETERS. 3. DIMENSION b DOES NOT INCLUDE DAMBAR
- PROTRUSION. DAMBAR PROTRUSION SHALL BE 0.10 MAX. AT MMC. DAMBAR CANNOT BE LOCATED ON THE LOWER RADIUS OF THE FOOT. DIMENSION 6 APPLIES TO THE FLAT SECTION OF THE LEAD BETWEEN 0.10 TO 0.25 FROM THE LEAD TIP.
- FROM THE LEAD TIP.
  DIMENSION D DOES NOT INCLUDE MOLD FLASH, PROTRUSIONS OR GATE BURRS. MOLD FLASH, PROTRUSIONS OR GATE BURRS SHALL NOT EXCEED 0.15 PER SIDE. DIMENSION D IS DETERMINED AT DATUM PLANE H.
  DIMENSION E1 DOES NOT INCLUDE INTERLEAD FLASH OR PROTRUSION. INTERLEAD FLASH OR DROTBUISION SHALL NOT EXCEED 0.25 PER
- OR PROTRUSION SHALL NOT EXCEED 0.25 PER SIDE. DIMENSION E1 IS DETERMINED AT DA-
- TUM PLANE H. 6. DATUMS A AND B ARE DETERMINED AT DATUM
- 7.
- DATUMS A AND B ARE DETERMINED AT DATE: PLANE H. A1 IS DEFINED AS THE VERTICAL DISTANCE FROM THE SEATING PLANE TO THE LOWEST POINT ON THE PACKAGE BODY. CONTOURS OF THE THERMAL PAD ARE UN-CONTROLLED WITHIN THE REGION DEFINED SY DIMENSIONS DO AND F2 8. BY DIMENSIONS D2 AND E2.

MILLIMETERS			
MIN MAX			
	1.70		
0.00	0.10		
0.19	0.30		
0.09	0.20		
	MIN  0.00 0.19		

D2	5.28	5.58		
E1	3.90	BSC		
E2	2.44	2.64		
е	0.65 BSC			
h	0.25	0.50		
L	0.40	0.85		
11	1.00 BEE			

0.25 BSC 0° 8 8

L2 M

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